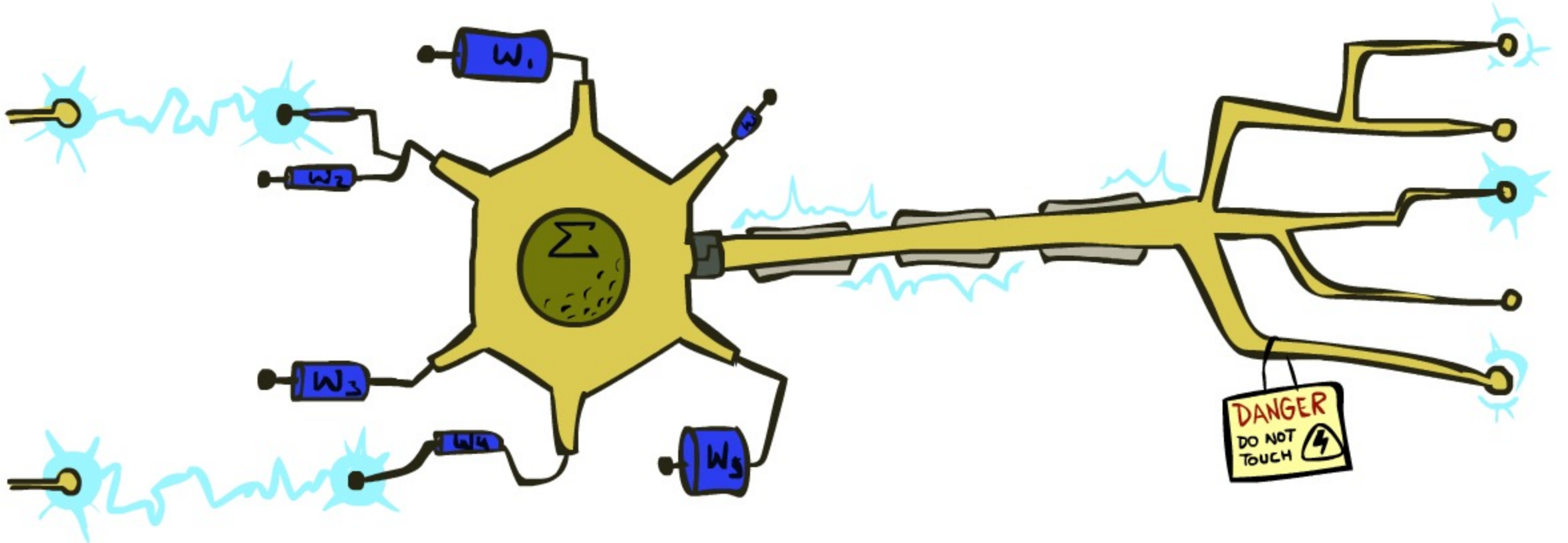


CS 188: Artificial Intelligence

Perceptrons and Logistic Regression

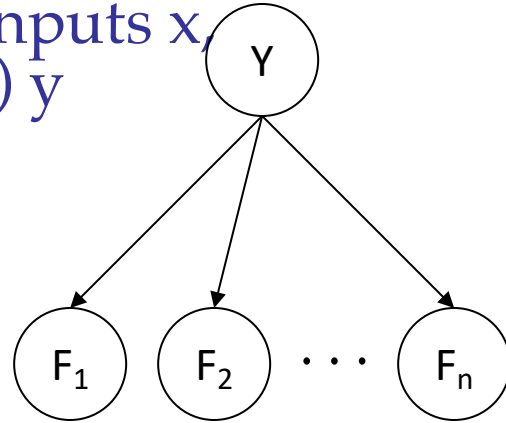


Instructor: Pieter Abbeel -- University of California, Berkeley

[These slides were created by Dan Klein, Pieter Abbeel, Anca Dragan, Sergey Levine. All CS188 materials are at <http://ai.berkeley.edu>.]

Last Time

- Classification: given inputs x , predict labels (classes) y



- Naïve Bayes

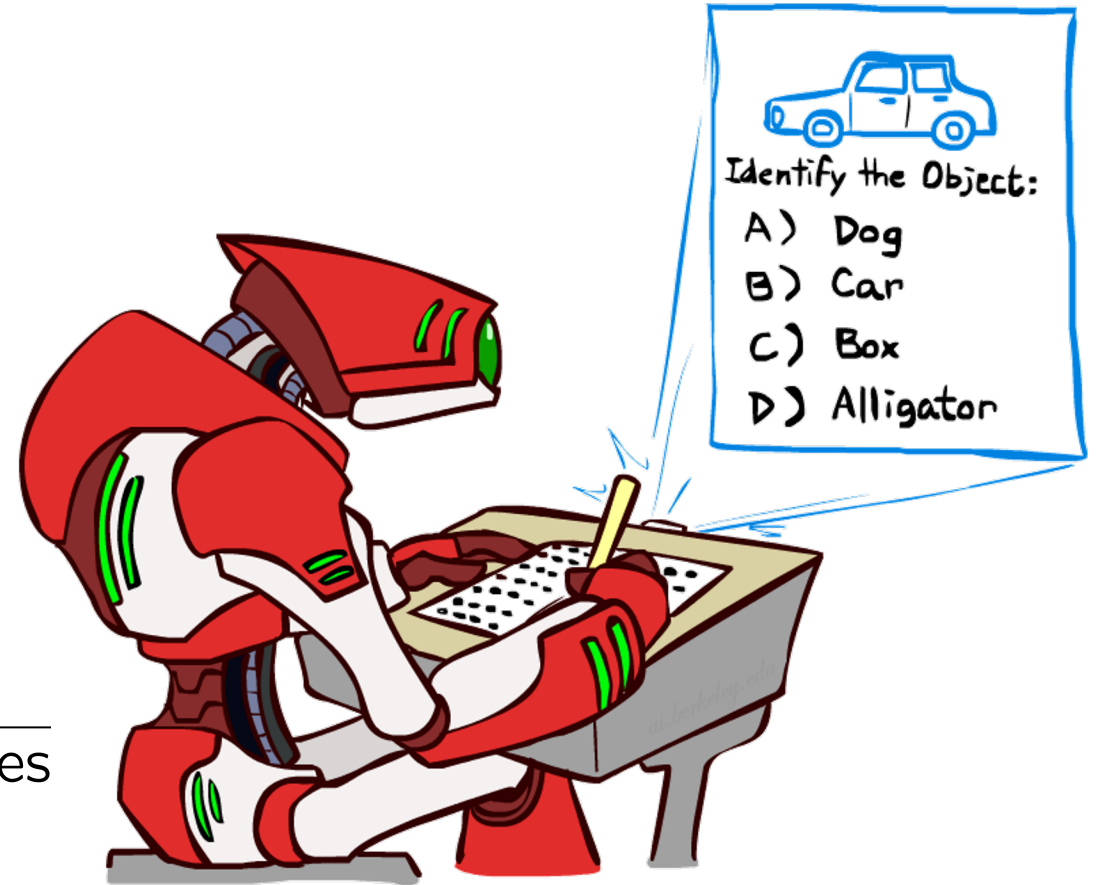
$$P(Y|F_{0,0} \dots F_{15,15}) \propto P(Y) \prod_{i,j} P(F_{i,j}|Y)$$

- Parameter estimation:

- MLE, MAP, priors $P_{\text{ML}}(x) = \frac{\text{count}(x)}{\text{total samples}}$

- Laplace smoothing $P_{\text{LAP},k}(x) = \frac{c(x) + k}{N + k|X|}$

- Training set, held-out set, test set



Workflow

- **Phase 1: Train model on Training Data. Choice points for “tuning”**
 - Attributes / Features
 - Model types: Naïve Bayes vs. Perceptron vs. Logistic Regression vs. Neural Net etc..
 - Model hyperparameters
 - E.g. Naïve Bayes – Laplace k
 - E.g. Logistic Regression – weight regularization
 - E.g. Neural Net – architecture, learning rate, ...
 - Make sure good performance on training data (why?)
- **Phase 2: Evaluate on Hold-Out Data**
 - If Hold-Out performance is close to Train performance
 - We achieved good generalization, onto Phase 3! 😊
 - If Hold-Out performance is much worse than Train performance
 - We overfitted to the training data! ☹
 - Take inspiration from the errors and:
 - Either: go back to Phase 1 for tuning (typically: make the model less expressive)
 - Or: if we are out of options for tuning while maintaining high train accuracy, collect more data (i.e., let the data drive generalization, rather than the tuning/regularization) and go to Phase 1
- **Phase 3: Report performance on Test Data**

Training
Data

Held-Out
Data

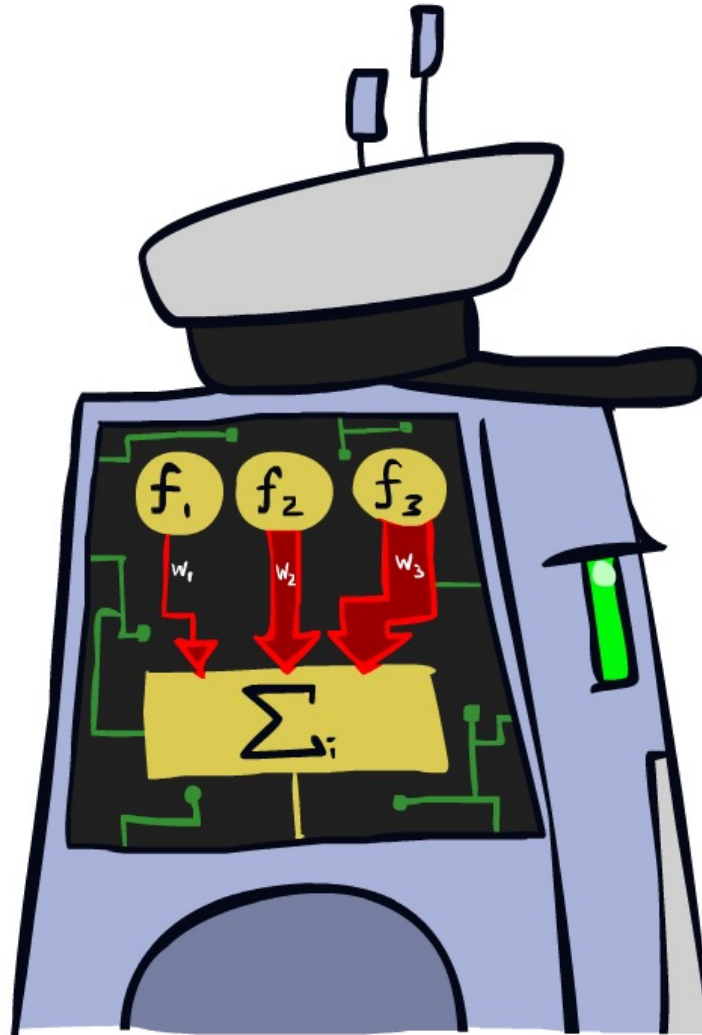
Test
Data

Possible outer-loop: Collect more data 😊

Practical Tip: Baselines

- First step: get a **baseline**
 - Baselines are very simple “straw man” procedures
 - Help determine how hard the task is
 - Help know what a “good” accuracy is
- Weak baseline: most frequent label classifier
 - Gives all test instances whatever label was most common in the training set
 - E.g. for spam filtering, might label everything as ham
 - Accuracy might be very high if the problem is skewed
 - E.g. calling everything “ham” gets 66%, so a classifier that gets 70% isn’t very good...
- For real research, usually use previous work as a (strong) baseline

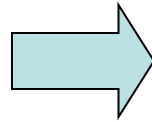
Linear Classifiers



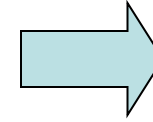
Feature Vectors

 x $f(x)$ y

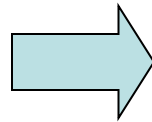
```
Hello,  
  
Do you want free printer  
cartridges? Why pay more  
when you can get them  
ABSOLUTELY FREE! Just
```



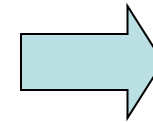
```
# free      : 2  
YOUR_NAME   : 0  
MISPELLED   : 2  
FROM_FRIEND : 0  
...
```



SPAM
or
+



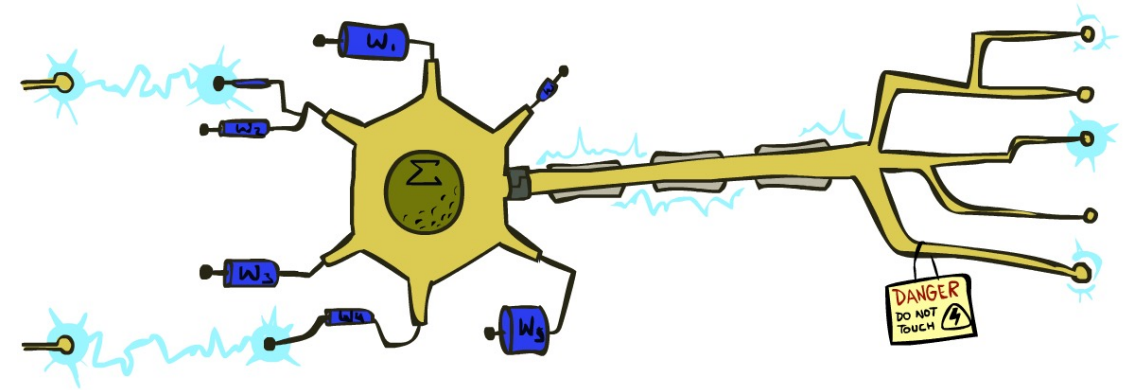
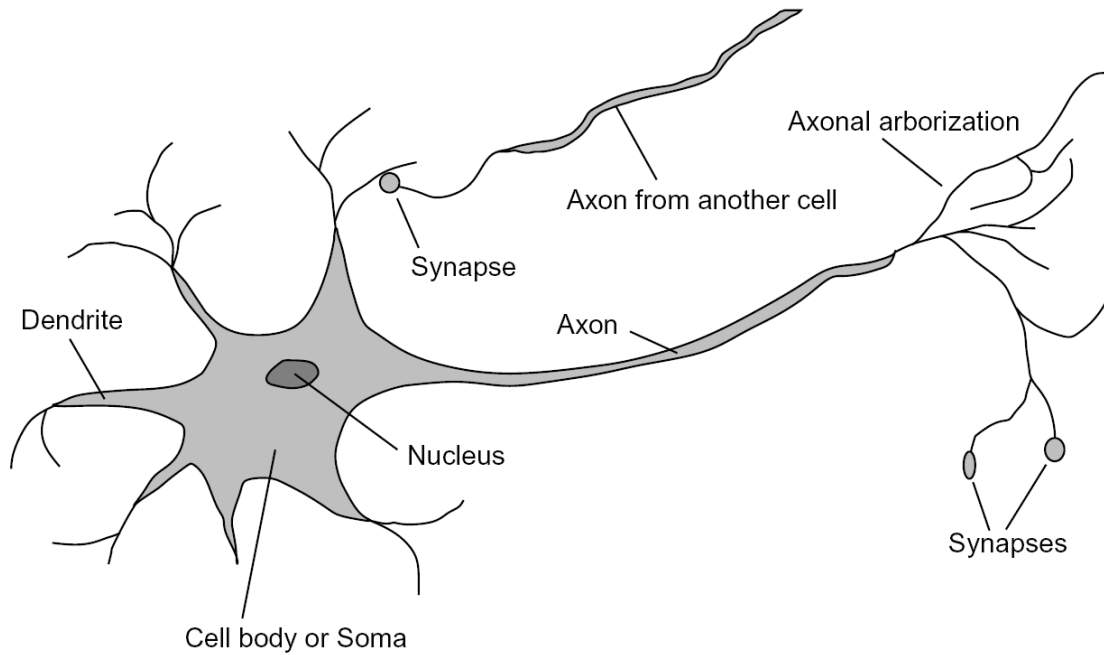
```
PIXEL-7,12 : 1  
PIXEL-7,13 : 0  
...  
NUM_LOOPS  : 1  
...
```



"2"

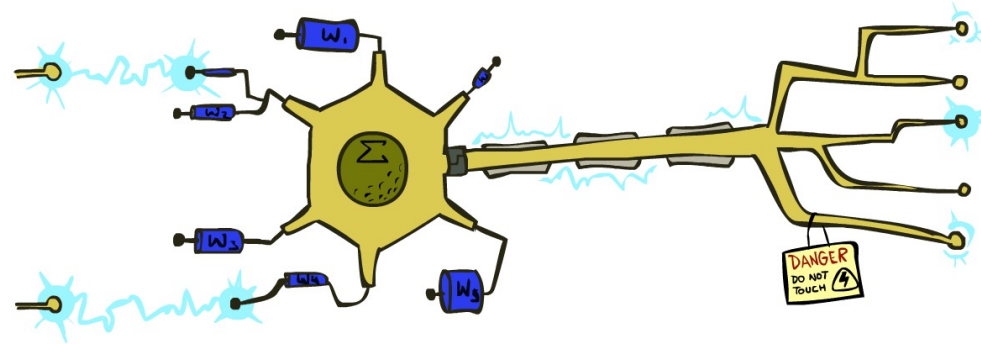
Some (Simplified) Biology

- Very loose inspiration: human neurons



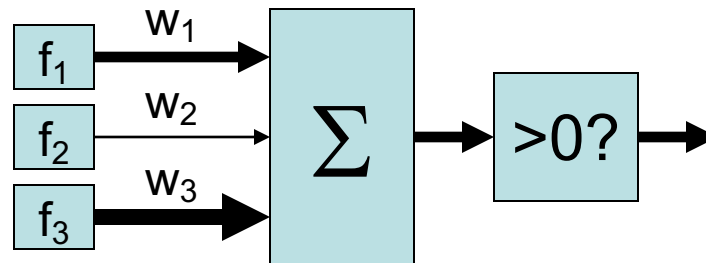
Linear Classifiers

- Inputs are **feature values**
- Each feature has a **weight**
- Sum is the **activation**



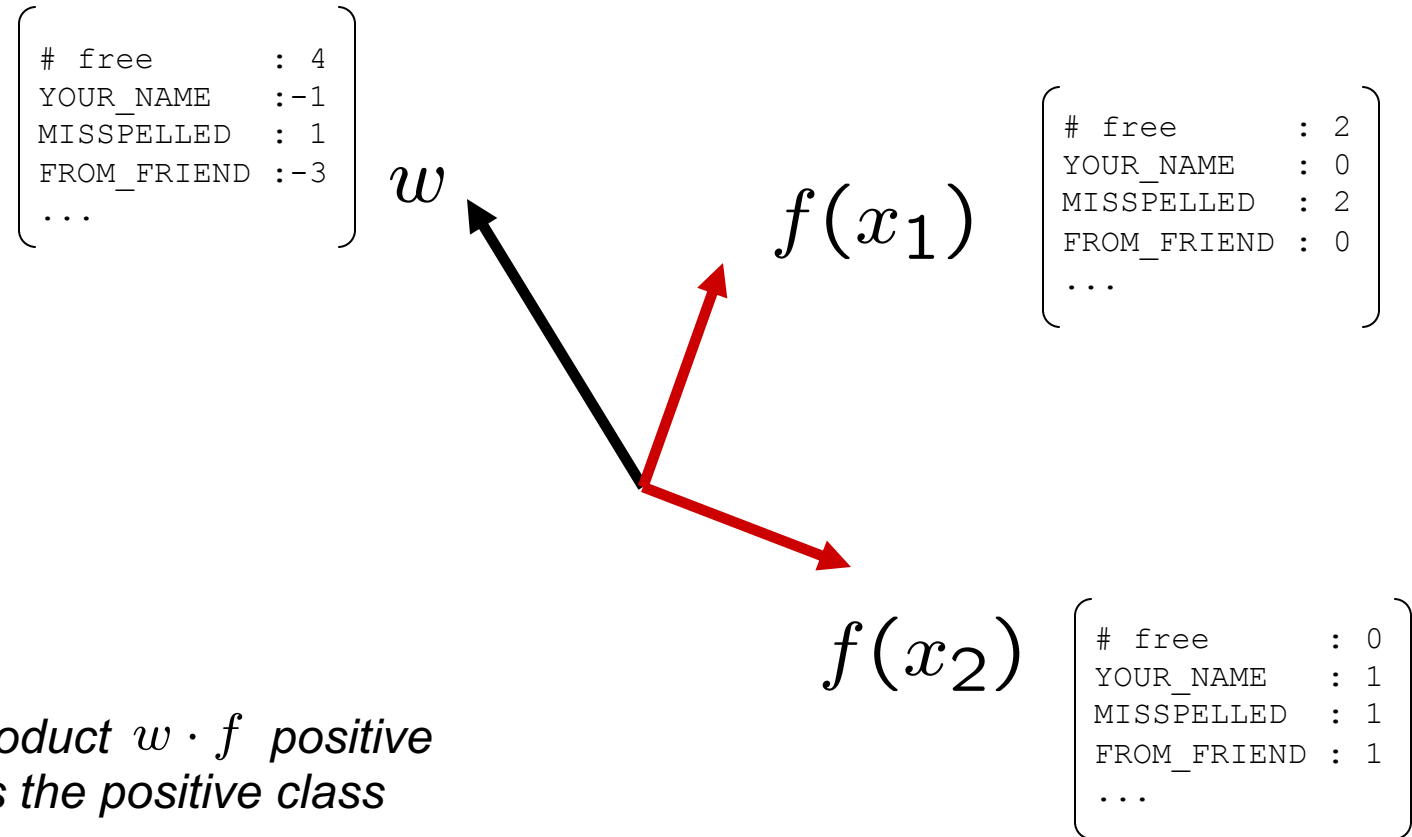
$$\text{activation}_w(x) = \sum_i w_i \cdot f_i(x) = w \cdot f(x)$$

- If the activation is:
 - Positive, output +1
 - Negative, output -1

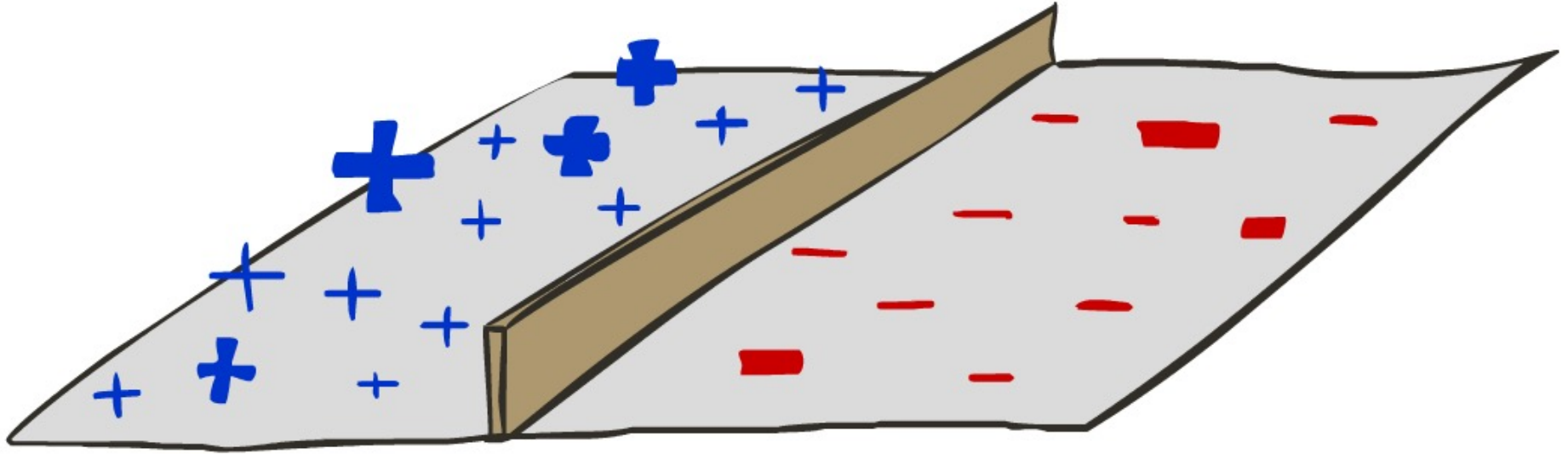


Weights

- Binary case: compare features to a weight vector
- Learning: figure out the weight vector from examples



Decision Rules

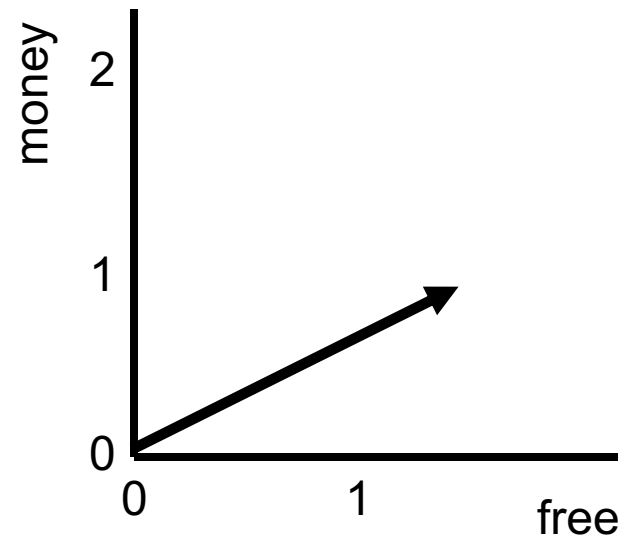
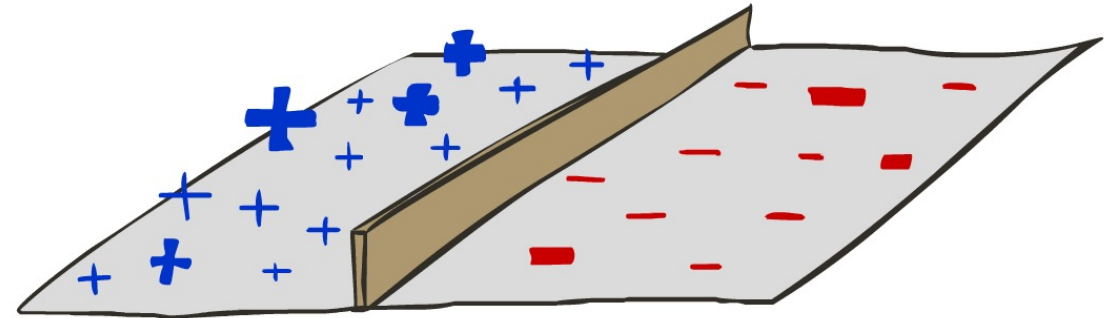


Binary Decision Rule

- In the space of feature vectors
 - Examples are points
 - Any weight vector is a hyperplane
 - One side corresponds to $Y=+1$
 - Other corresponds to $Y=-1$

w

BIAS	:	-3
free	:	4
money	:	2
...		

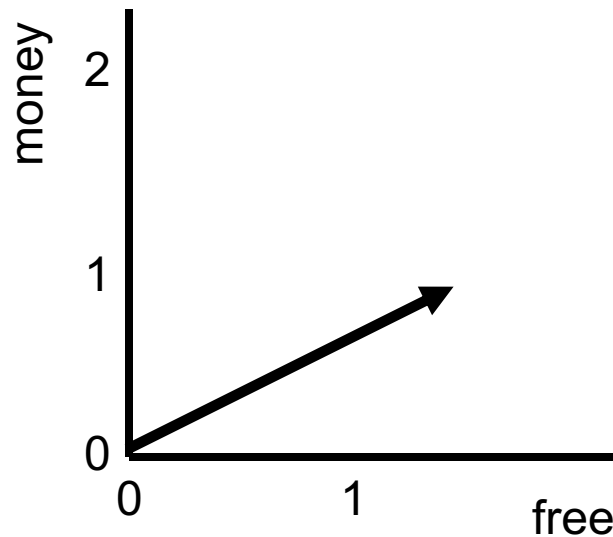
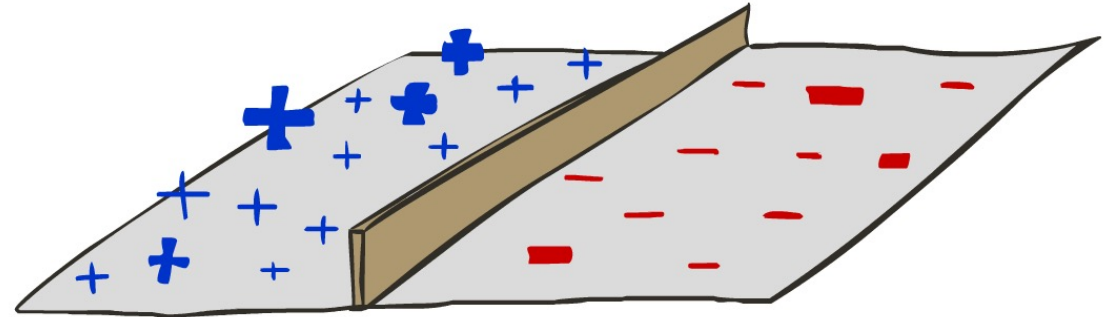


Binary Decision Rule

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w

free	:	4
money	:	2

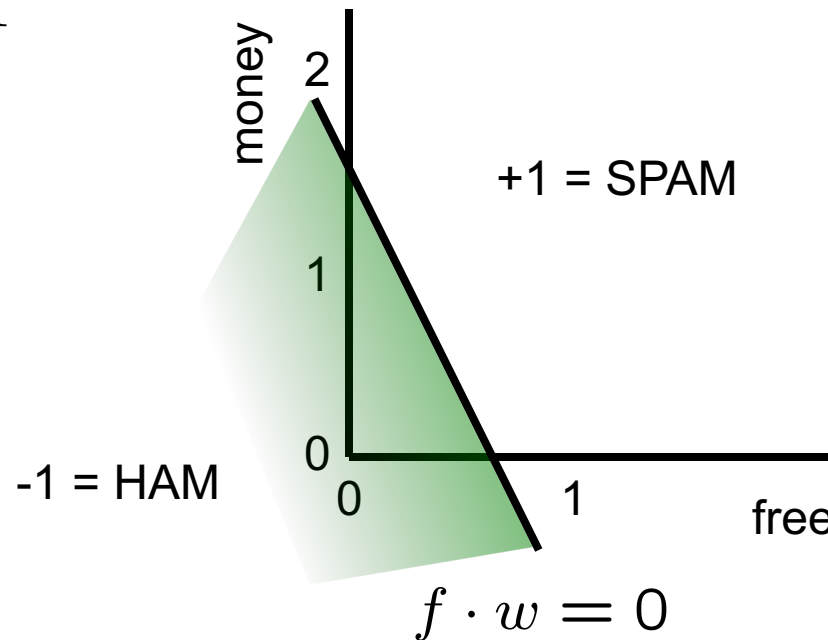
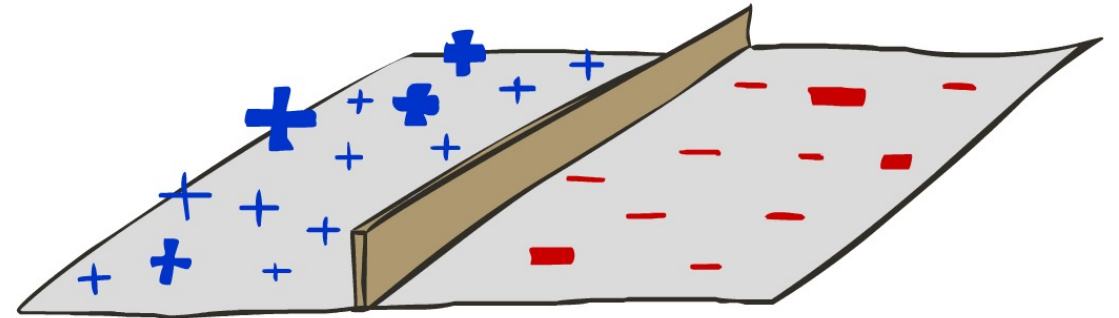


Binary Decision Rule

- In the space of feature vectors
 - Examples are points
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w

BIAS	:	-3
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...		

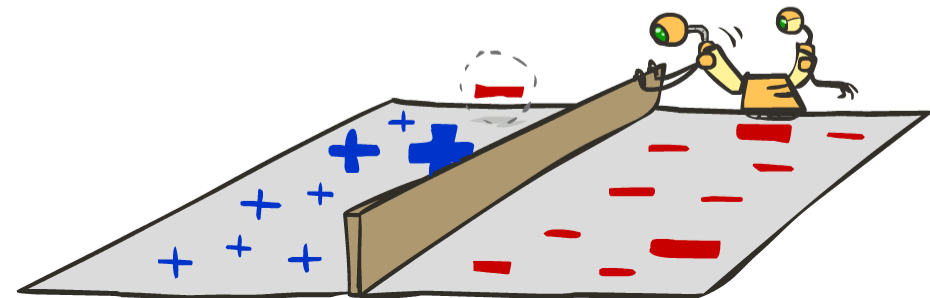
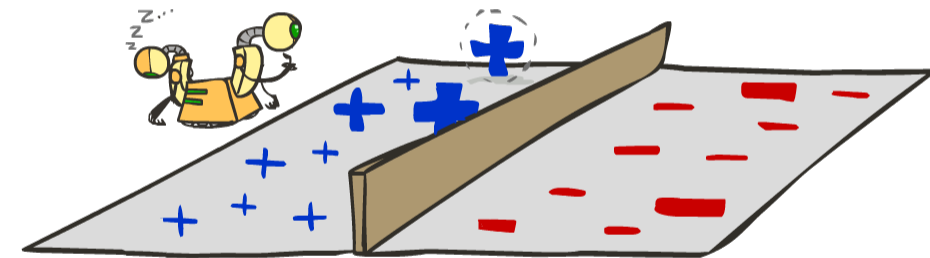
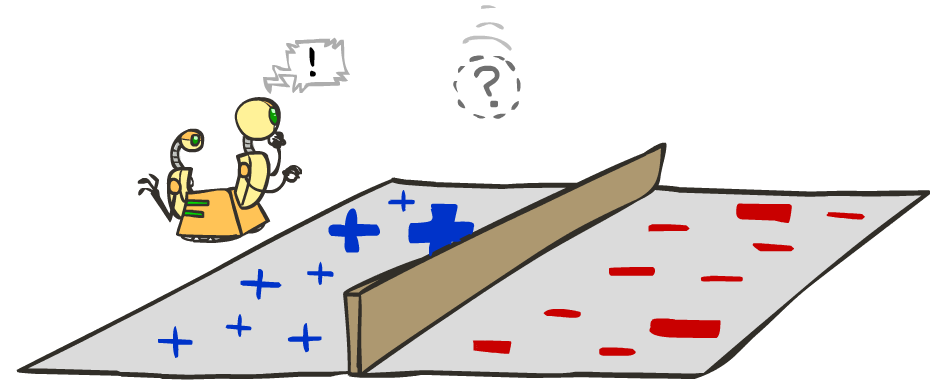


Weight Updates



Learning: Binary Perceptron

- Start with weights = 0
- For each training instance:
 - Classify with current weights
- If correct (i.e., $y=y^*$), no change!
- If wrong: adjust the weight vector



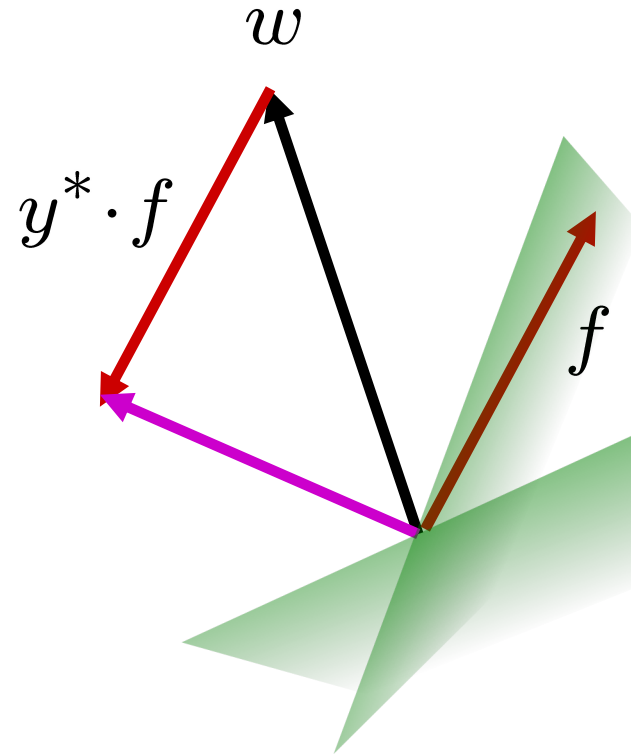
Learning: Binary Perceptron

- Start with weights = 0
- For each training instance:
 - Classify with current weights

$$y = \begin{cases} +1 & \text{if } w \cdot f(x) \geq 0 \\ -1 & \text{if } w \cdot f(x) < 0 \end{cases}$$

- If correct (i.e., $y=y^*$), no change!
- If wrong: adjust the weight vector by adding or subtracting the feature vector. Subtract if y^* is -1.

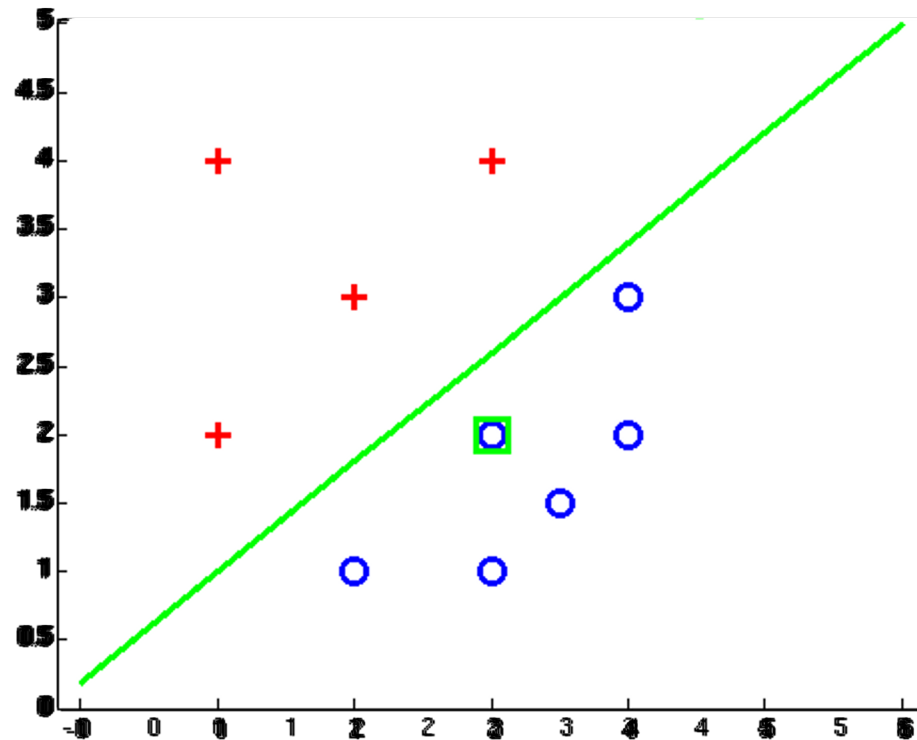
$$w = w + y^* \cdot f$$



Before: $w \cdot f$
After: $w \cdot f + y^* \cdot f$
 $f \cdot f \geq 0$

Examples: Perceptron

- Separable Case



Multiclass Decision Rule

- If we have multiple classes:
 - A weight vector for each class:

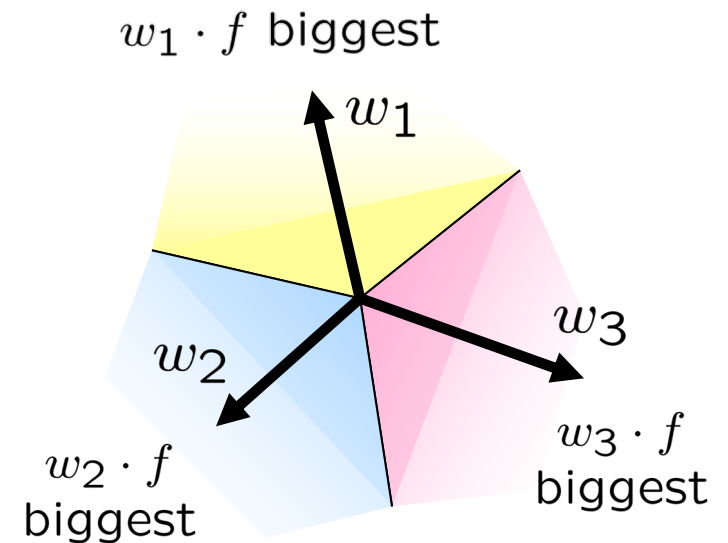
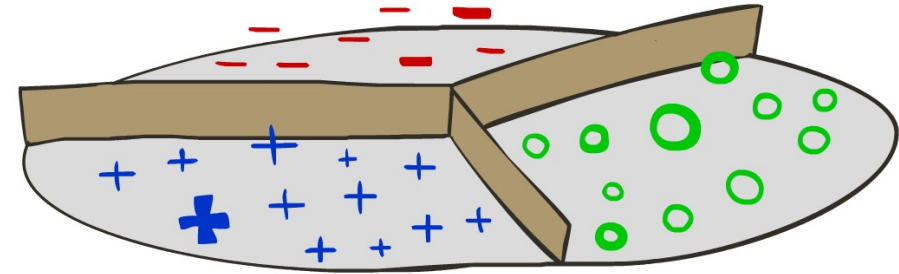
$$w_y$$

- Score (activation) of a class y :

$$w_y \cdot f(x)$$

- Prediction highest score wins

$$y = \arg \max_y w_y \cdot f(x)$$



Binary = multiclass where the negative class has weight zero

Learning: Multiclass Perceptron

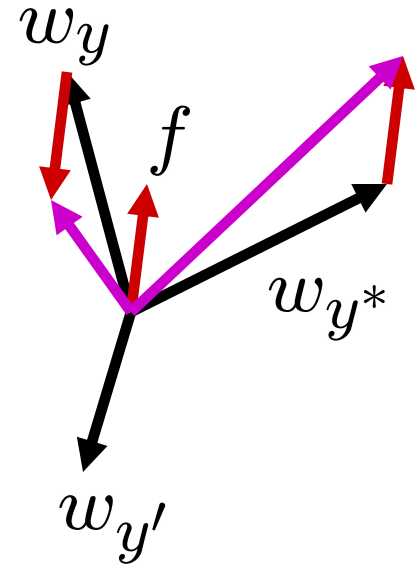
- Start with all weights = 0
- Pick up training examples one by one
- Predict with current weights

$$y = \arg \max_y w_y \cdot f(x)$$

- If correct, no change!
- If wrong: lower score of wrong answer, raise score of right answer

$$w_y = w_y - f(x)$$

$$w_{y^*} = w_{y^*} + f(x)$$



Example: Multiclass Perceptron

“win the vote” [1 1 0 1 1]

“win the election” [1 1 0 0 1]

“win the game” [1 1 1 0 1]

w_{SPORTS}

	1	-2	-2
BIAS : 1	0		1
win : 0	-1		0
game : 0	0		1
vote : 0	-1		-1
the : 0	-1		0
...			

$w_{POLITICS}$

	0	3	3
BIAS : 0	1		0
win : 0	1		0
game : 0	0		-1
vote : 0	1		1
the : 0	1		0
...			

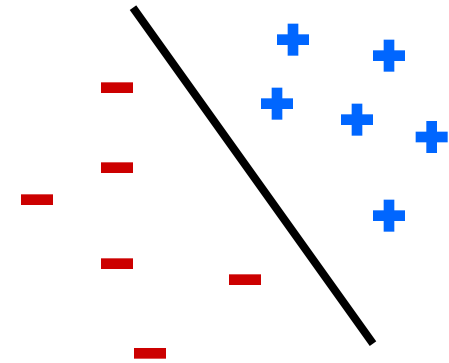
w_{TECH}

	0	0
BIAS : 0		
win : 0		
game : 0		
vote : 0		
the : 0		
...		

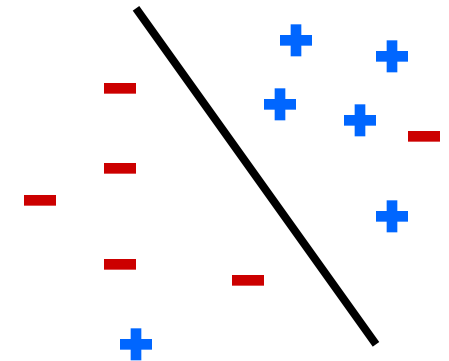
Properties of Perceptrons

- Separability: true if some parameters get the training set perfectly correct
- Convergence: if the training is separable, perceptron will eventually converge (binary case)
- Mistake Bound: the maximum number of mistakes (binary case) related to the *margin* or degree of separability

Separable

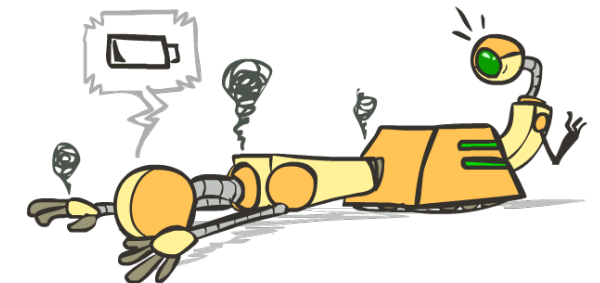
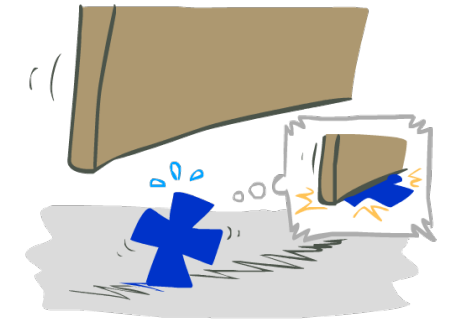
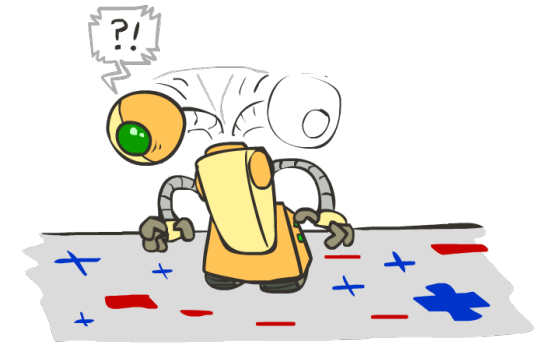
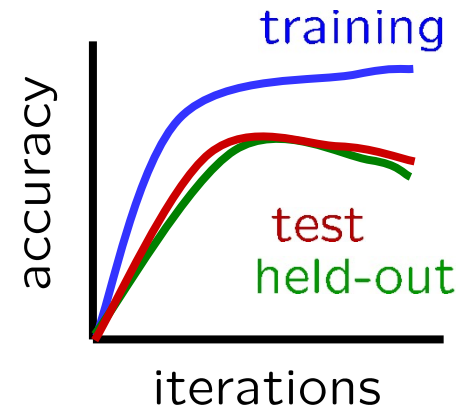
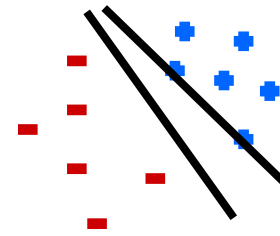
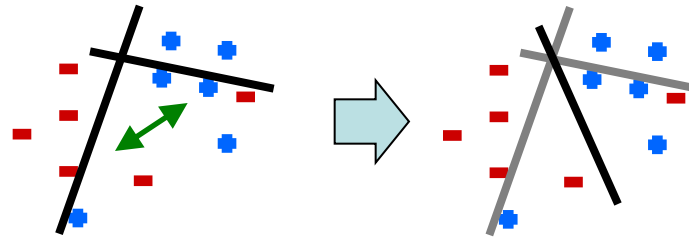


Non-Separable

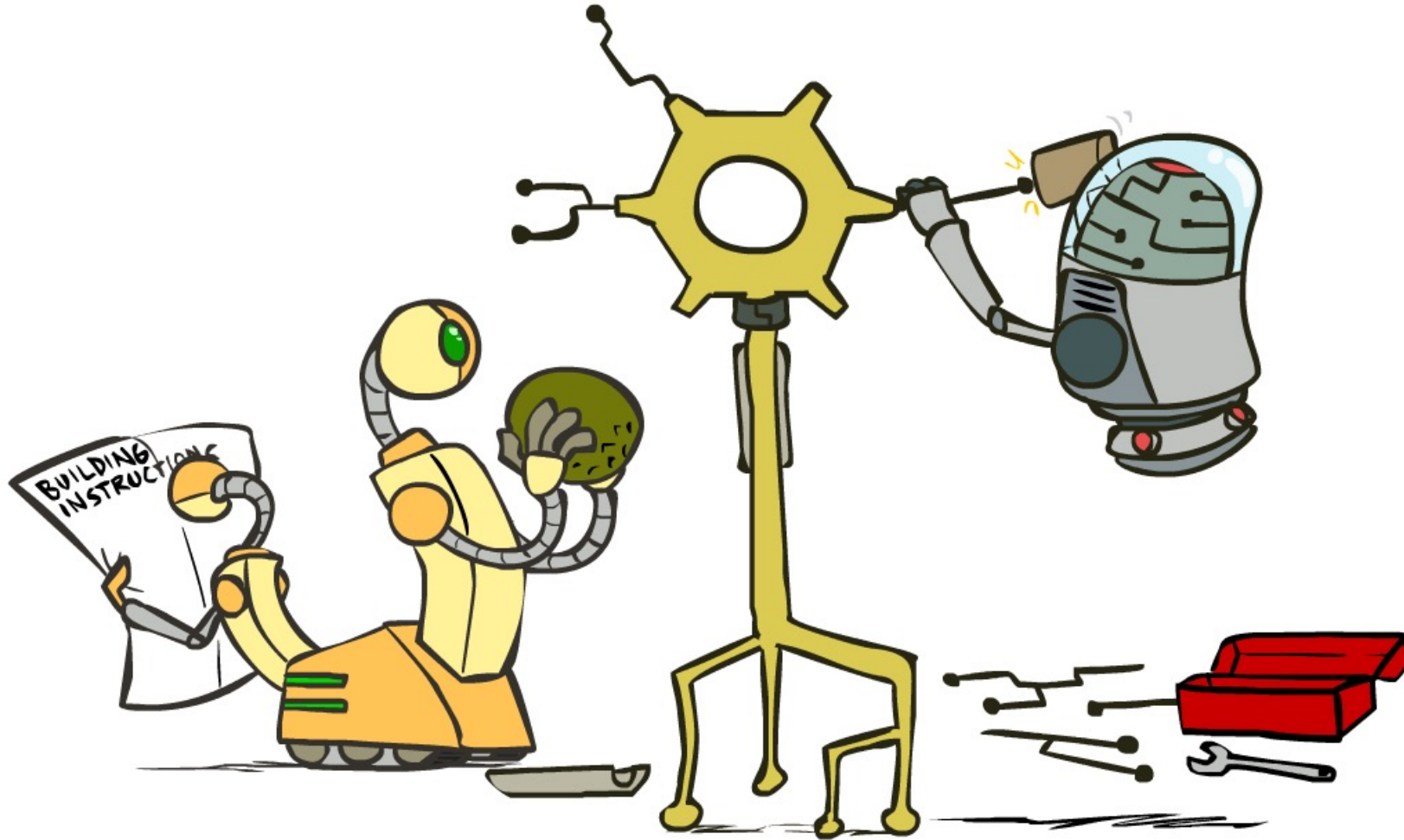


Problems with the Perceptron

- Noise: if the data isn't separable, weights might thrash
 - Averaging weight vectors over time can help (averaged perceptron)
- Mediocre generalization: finds a "barely" separating solution
- Overtraining: test / held-out accuracy usually rises, then falls
 - Overtraining is a kind of overfitting

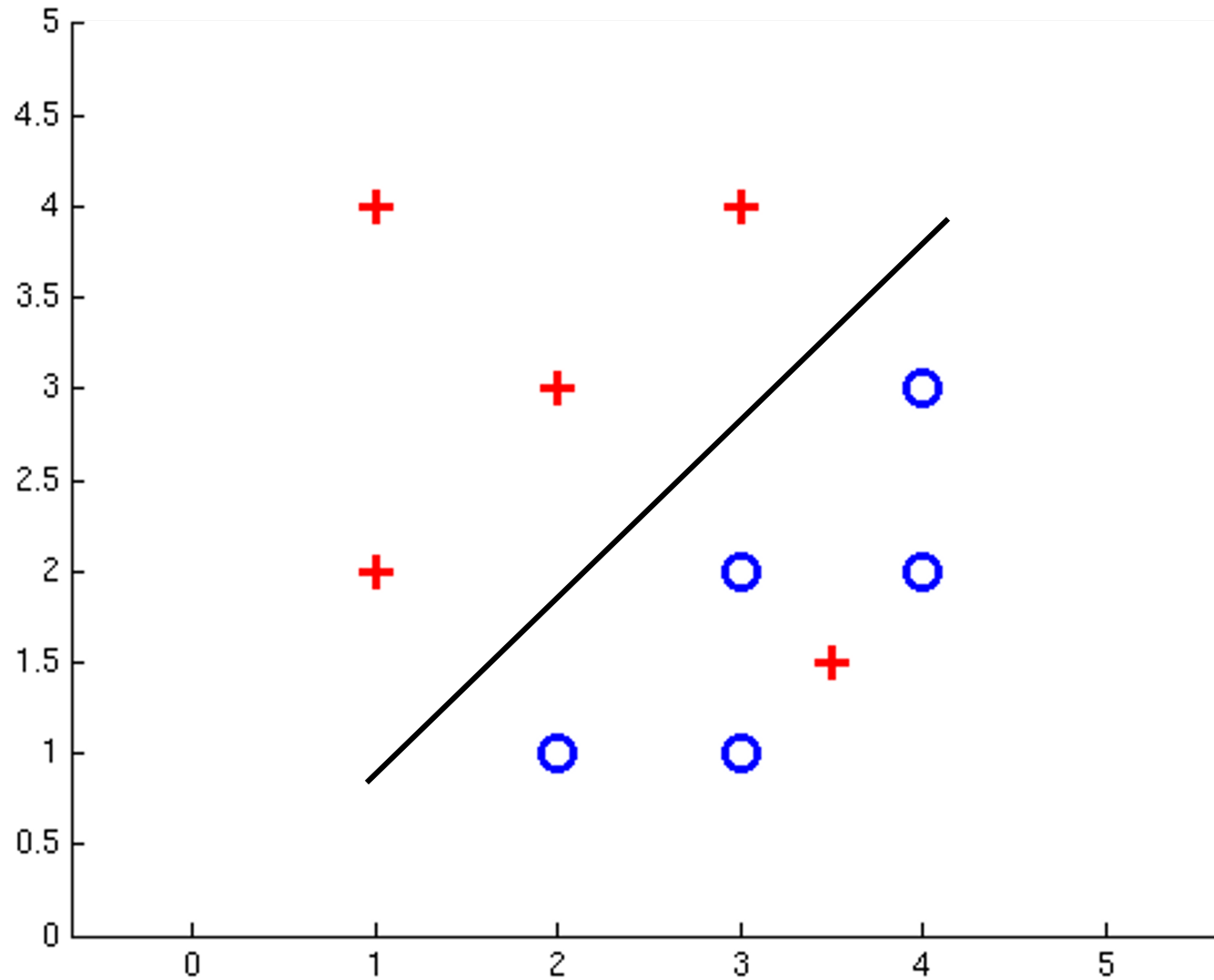


Improving the Perceptron

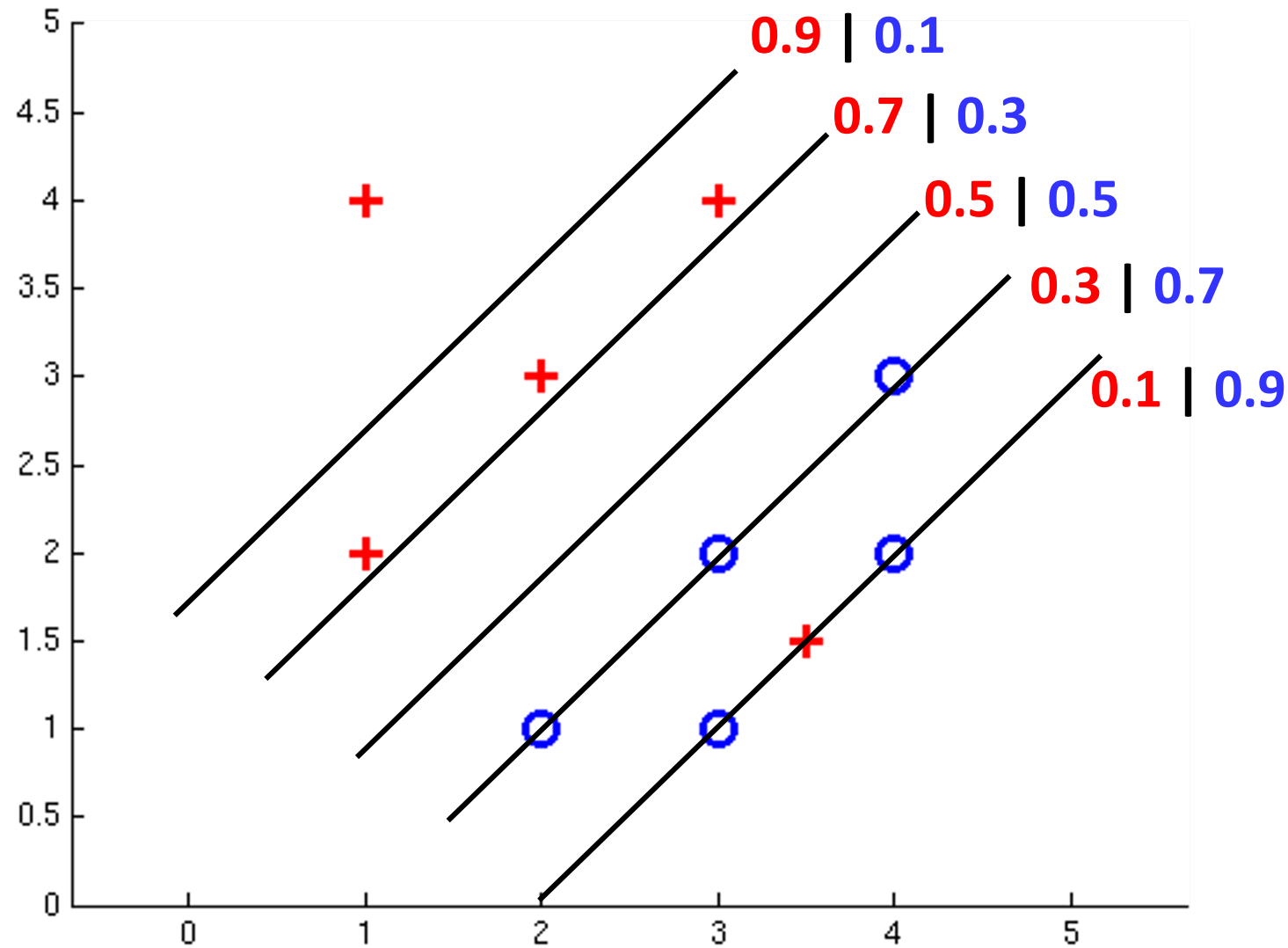


Non-Separable Case: Deterministic Decision

Even the best linear boundary makes at least one mistake



Non-Separable Case: Probabilistic Decision

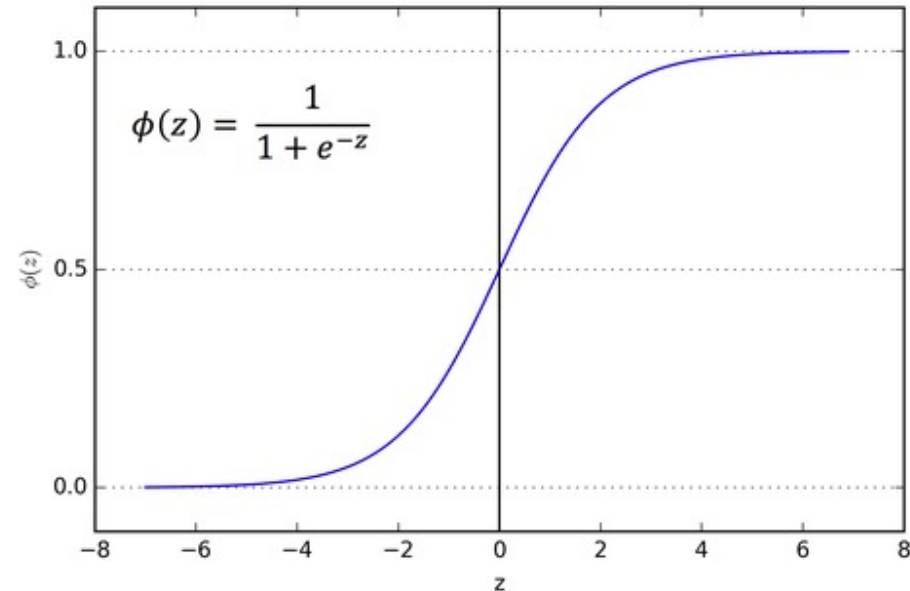


How to get probabilistic decisions?

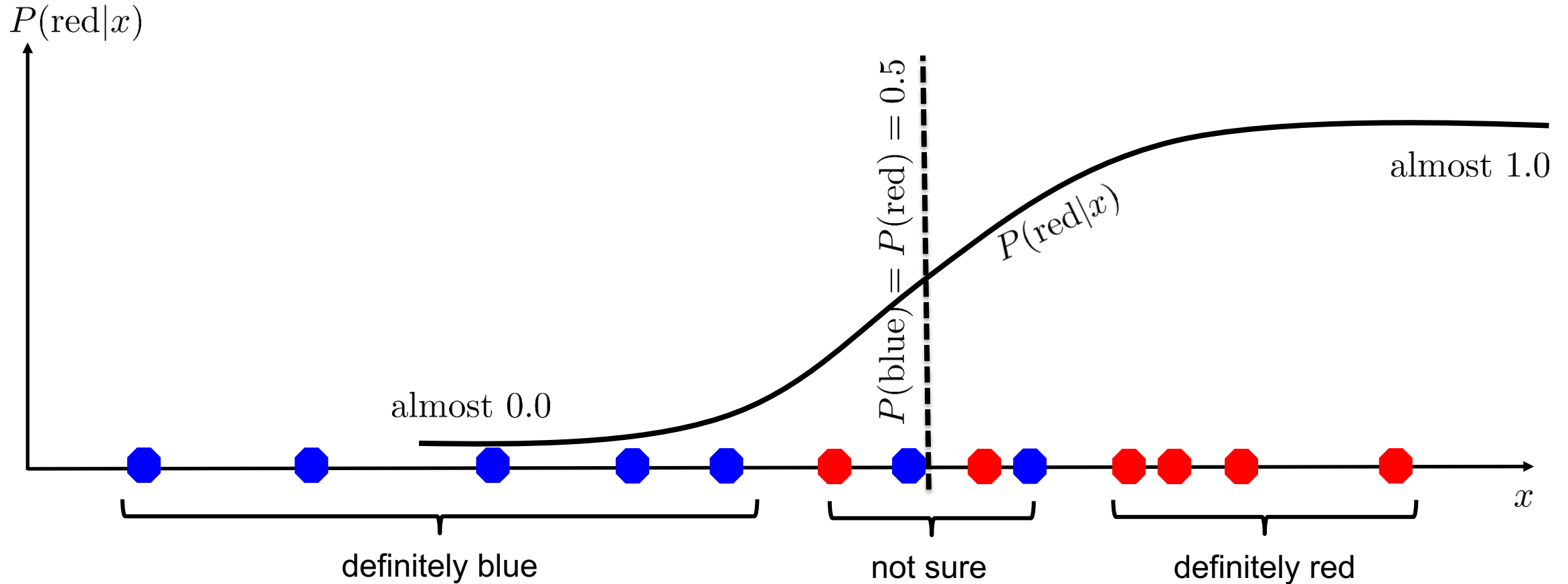
- Perceptron scoring: $z = w \cdot f(x)$
- If $z = w \cdot f(x)$ very positive $\rightarrow$ want probability going to 1
- If $z = w \cdot f(x)$ very negative $\rightarrow$ want probability going to 0

- Sigmoid function

$$\phi(z) = \frac{1}{1 + e^{-z}}$$



A 1D Example

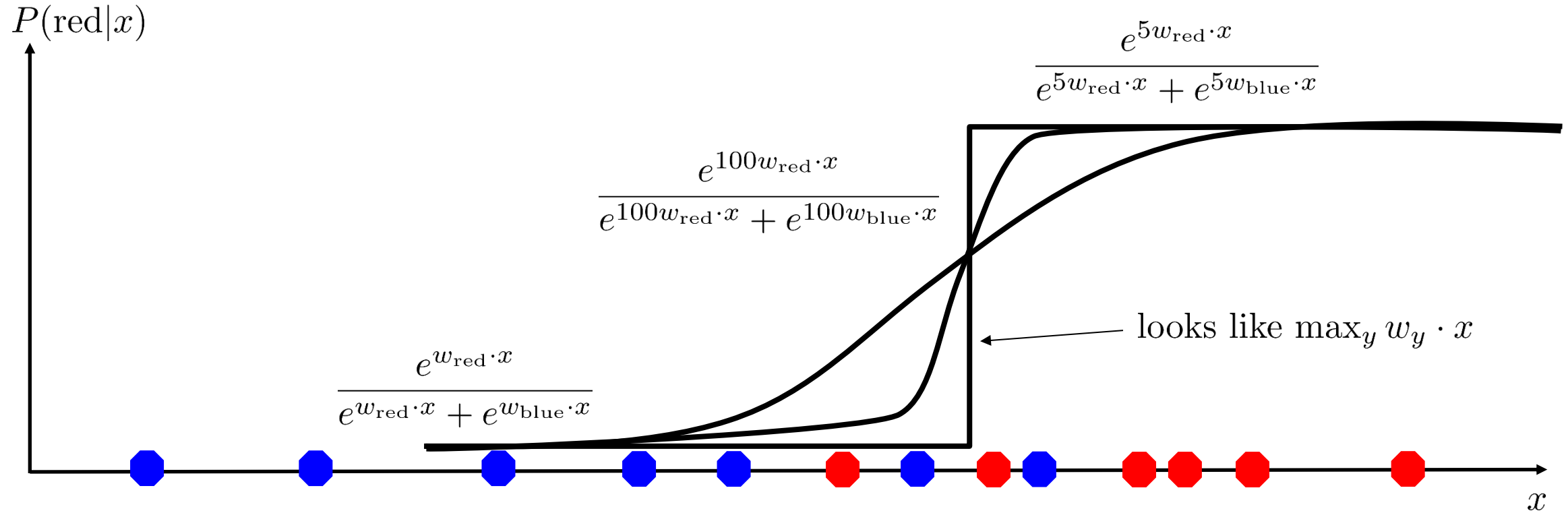


$$P(\text{red}|x) = \frac{e^{w_{\text{red}} \cdot x}}{e^{w_{\text{red}} \cdot x} + e^{w_{\text{blue}} \cdot x}}$$

probability increases exponentially as we move away from boundary

normalizer

The *Soft* Max



$$P(\text{red}|x) = \frac{e^{w_{\text{red}} \cdot x}}{e^{w_{\text{red}} \cdot x} + e^{w_{\text{blue}} \cdot x}}$$

Best w ?

- Maximum likelihood estimation:

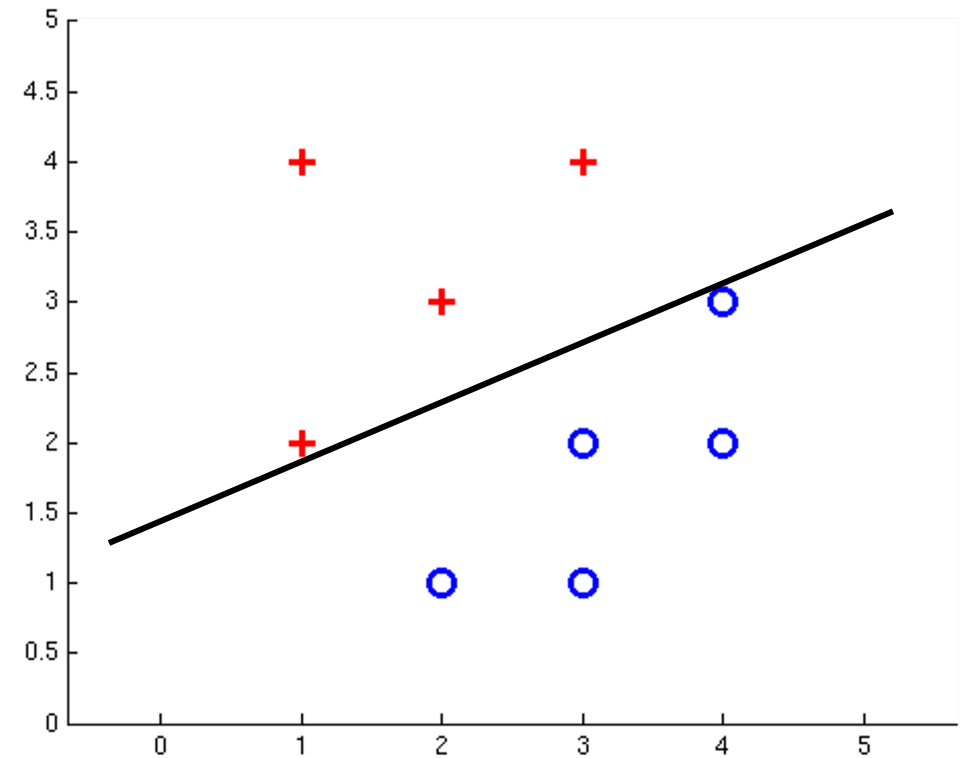
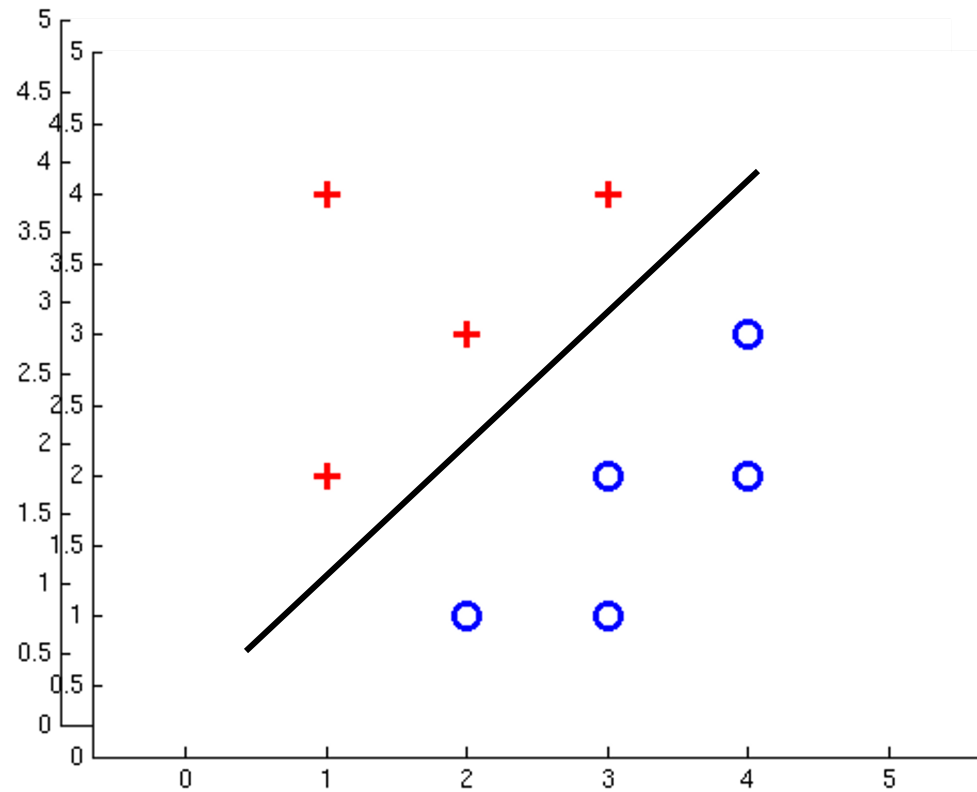
$$\max_w ll(w) = \max_w \sum_i \log P(y^{(i)} | x^{(i)}; w)$$

with:

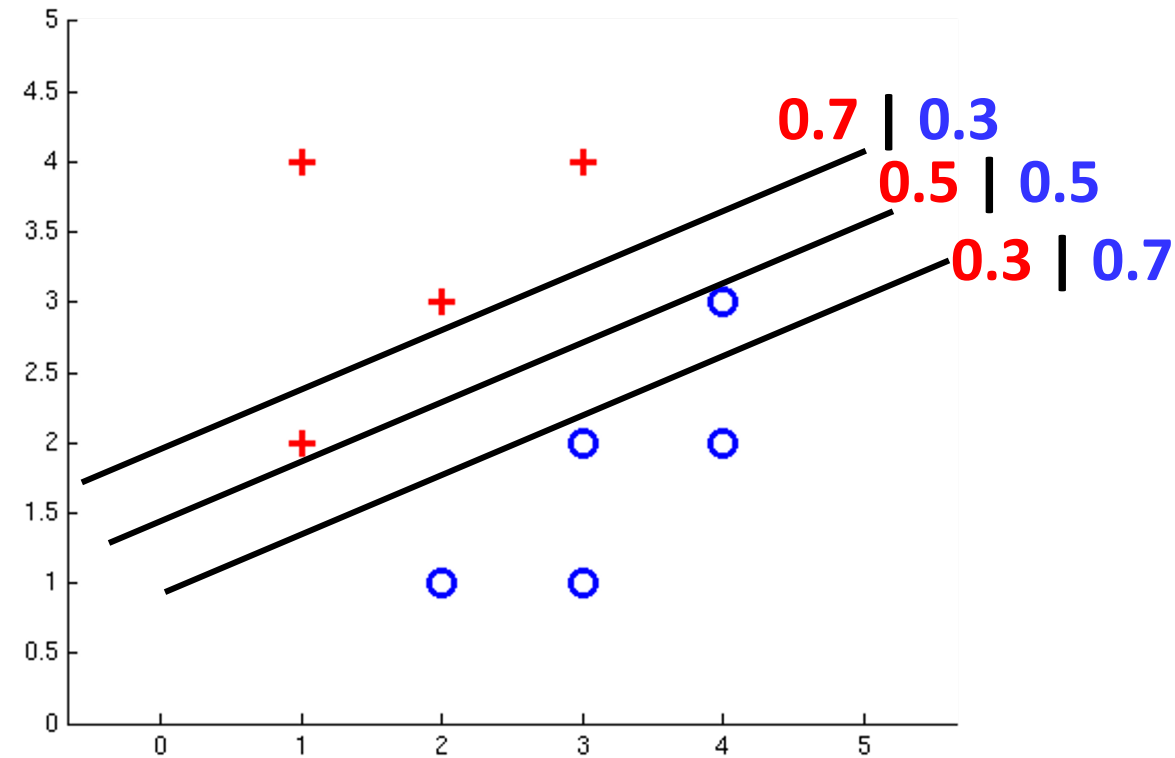
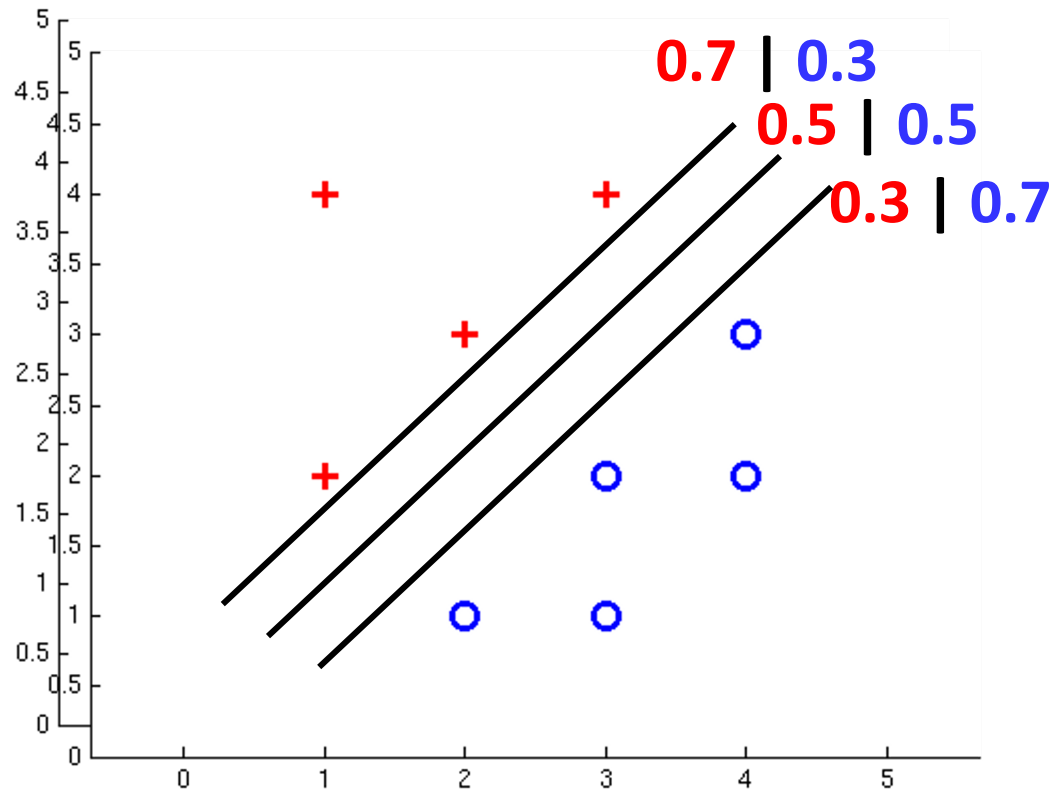
$$P(y^{(i)} = +1 | x^{(i)}; w) = \frac{1}{1 + e^{-w \cdot f(x^{(i)})}}$$
$$P(y^{(i)} = -1 | x^{(i)}; w) = 1 - \frac{1}{1 + e^{-w \cdot f(x^{(i)})}}$$

= Logistic Regression

Separable Case: Deterministic Decision – Many Options



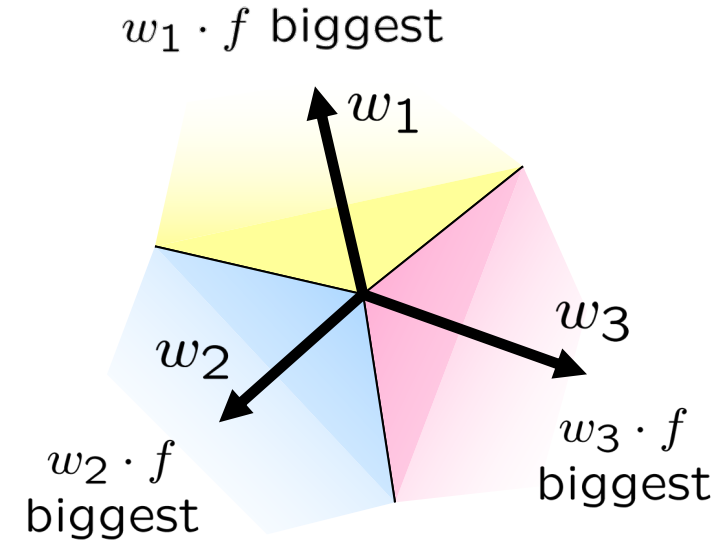
Separable Case: Probabilistic Decision – Clear Preference



Multiclass Logistic Regression

- Recall Perceptron:

- A weight vector for each class: w_y
- Score (activation) of a class y : $w_y \cdot f(x)$
- Prediction highest score wins $y = \arg \max_y w_y \cdot f(x)$



- How to make the scores into probabilities?

$$\underbrace{z_1, z_2, z_3}_{\text{original activations}} \rightarrow \underbrace{\frac{e^{z_1}}{e^{z_1} + e^{z_2} + e^{z_3}}, \frac{e^{z_2}}{e^{z_1} + e^{z_2} + e^{z_3}}, \frac{e^{z_3}}{e^{z_1} + e^{z_2} + e^{z_3}}}_{\text{softmax activations}}$$

Best w ?

- Maximum likelihood estimation:

$$\max_w ll(w) = \max_w \sum_i \log P(y^{(i)} | x^{(i)}; w)$$

with:

$$P(y^{(i)} | x^{(i)}; w) = \frac{e^{w_{y^{(i)}} \cdot f(x^{(i)})}}{\sum_y e^{w_y \cdot f(x^{(i)})}}$$

= Multi-Class Logistic Regression

Next Lecture

- Optimization

- i.e., how do we solve:

$$\max_w ll(w) = \max_w \sum_i \log P(y^{(i)} | x^{(i)}; w)$$